

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

APPLICATION FOR UNITED STATES PATENT

FOR

**SINGLE CRYSTAL SILICON SENSOR  
WITH ADDITIONAL LAYER AND  
METHOD OF PRODUCING THE SAME**

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**SINGLE CRYSTAL SILICON SENSOR  
WITH ADDITIONAL LAYER AND  
METHOD OF PRODUCING THE SAME**

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**FIELD OF THE INVENTION**

The invention generally relates to sensors and, more particularly, the invention relates to single crystal silicon sensors.

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**BACKGROUND OF THE INVENTION**

Microelectromechanical systems ("MEMS") are used in a growing number of applications. For example, MEMS currently are implemented as gyroscopes to detect pitch angles of airplanes, and as accelerometers to selectively deploy air bags in automobiles. In simplified terms, many such MEMS devices often have a structure suspended above a substrate, and associated circuitry that both senses movement of the suspended structure and delivers the sensed movement data to one or more external devices (e.g., an external computer). The external device processes the sensed data to calculate the property being measured (e.g., pitch angle or acceleration).

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Many types of MEMS sensors, such as those discussed above, are manufactured by means of conventional surface micromachining ("SMM") techniques. As known by those skilled in the art, surface micromachining techniques build material layers on top of a substrate using additive and subtractive processes. Typically, SMM techniques use polysilicon to fabricate the MEMS sensors.

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Rather than use polysilicon, however, MEMS sensors also can be fabricated from single crystal silicon. Among other benefits, use of single crystal

silicon facilitates integration of circuitry directly on the MEMS wafer. In some applications, however, MEMS sensors produced from single crystal silicon present a set of additional problems. For example, during design and manufacture, it may be more cumbersome to electrically interconnect some parts of the MEMS device. In addition, single crystal silicon MEMS sensors known to the inventors do not permit out of plane sensing and actuation.

### SUMMARY OF THE INVENTION

In accordance with one aspect of the invention, a silicon-on-insulator ("SOI") based MEMS device has a base layer, a device layer, and an insulator layer between the base layer and the device layer. The device also has a deposited layer having a portion that is spaced from the device layer. The device layer is between the insulator layer and the deposited layer.

The device may have an anchor extending from the deposited layer to contact the device layer. In some embodiments, the device layer includes circuitry. Such circuitry may be capable of operating after being subjected to the deposition temperature of the deposited layer. For example, the deposited layer may include germanium (e.g., silicon germanium, which has a relatively low deposition temperature).

In some embodiments, an air space separates the device layer from the deposited layer. The device layer also may have a top surface with given material formed thereon (e.g., metal leads). Such embodiments may separate the given material from the deposited layer by means of the air space.

In accordance with another aspect of the invention, a MEMS inertial sensor has a single crystal silicon layer with a top surface, and a deposited additional layer adjacent the top surface of the single crystal silicon layer. The single crystal silicon layer also has sensing structure. The deposited additional layer has a portion that is spaced from the top surface.

The deposited additional layer also may have a portion that contacts the top surface. Moreover, the deposited additional layer may include germanium or other material having a relatively low deposition temperature. The single crystal silicon layer also may be a part of a silicon-on-insulator wafer, where the sensor  
5 further includes a base layer and an insulator layer separating the base layer and the single crystal silicon layer.

In some embodiments, the single crystal silicon layer is a part of a bulk silicon wafer. Moreover, the deposited additional layer may form interconnects. In some embodiments, the sensing structure includes a movable member spaced  
10 from the deposited additional layer by an air space. In other embodiments, the deposited additional layer forms an electrode capable of capacitively coupling with at least a portion of the single crystal silicon layer.

In accordance with another aspect of the invention, a method of forming an SOI-based MEMS device provides a SOI-based MEMS wafer having a top  
15 face, and deposits a sacrificial layer on the top face. The method also deposits an additional MEMS layer on the sacrificial layer.

The additional MEMS layer may include a material having a deposition temperature that is less than about 450 degrees C. Moreover, the method further may remove at least a portion of the sacrificial layer. Among other things, the  
20 additional MEMS layer may form a cap for at least a portion of the top face of the SOI-based MEMS wafer. In illustrative embodiments, the method applies surface micromachining processes to the additional MEMS layer.

In accordance with another aspect of the invention, a method of forming a MEMS inertial sensor provides a single crystal wafer having a top face, and then  
25 deposits a sacrificial layer on the top face. An additional MEMS layer then is deposited on the sacrificial layer.

## BRIEF DESCRIPTION OF THE DRAWINGS

The foregoing and advantages of the invention will be appreciated more fully from the following further description thereof with reference to the accompanying drawings wherein:

Figure 1 schematically shows a cross-sectional view of a sensor produced in accordance with illustrative embodiments of the invention.

Figure 2 schematically shows a partial top view of the sensor shown in figure 1.

Figure 3 shows a process of forming the sensor shown in figure 1 in accordance with illustrative embodiments of the invention.

Figure 4 schematically shows the sensor of figure 1 during a stage of production (i.e., during step 300 of figure 3).

Figure 5 schematically shows the sensor of figure 1 during a stage of production (i.e., during step 302 of figure 3).

Figure 6 schematically shows the sensor of figure 1 during a stage of production (i.e., during step 304 of figure 3).

Figure 7 schematically shows the sensor of figure 1 during a stage of production (i.e., during step 306 of figure 3).

Figure 8 schematically shows the sensor of figure 1 during a stage of production (i.e., during step 308 of figure 3).

Figure 9 schematically shows the sensor of figure 1 during a stage of production (i.e., during step 310 of figure 3).

## DESCRIPTION OF ILLUSTRATIVE EMBODIMENTS

Illustrative embodiments of the invention combine single crystal silicon processes with conventional surface micromachining techniques to form a highly

functional sensor. More specifically, a sensor formed on a single crystal silicon wafer can have one or more additional deposited layers that can be micromachined to perform a number of supplemental functions. Among other things, an additional deposited layer can form a cap, interconnects between  
5 different portions of the sensor, or electrostatic actuation and detection devices. Details of various embodiments are discussed below.

Figure 1 schematically shows a cross-sectional view of an inertial sensor ("sensor 10") produced in accordance with illustrative embodiments of the invention. As discussed below, the sensor 10 is formed from a silicon-on-  
10 insulator wafer 12 ("SOI"), which has an insulator layer 14 formed between two single crystal silicon wafers. A first of the two wafers, referred to in the art as the "handle wafer 16," supports the insulator layer 14 and the second wafer. The insulator layer 14, typically an oxide, acts as a sacrificial layer during the sensor fabrication process. The second wafer, referred to in the art as the "device layer  
15 18," has both circuitry 20 and movable structure 22 that cooperate to detect sensor movement.

It should be noted that SOI technology is discussed herein as exemplary and is not intended to limit the scope of some embodiments. For example, other technologies implementing single crystal silicon devices can be used.

20 In illustrative embodiments, the inertial sensor 10 has circuitry 20 and structure 22 to form a MEMS accelerometer or gyroscope. Of course, other embodiments may be used with other types of devices, such as MEMS pressure sensors. In fact, some embodiments may be used with non-MEMS devices or general integrated circuits. Accordingly, discussion of specific types of inertial  
25 sensors, such as MEMS accelerometers and gyroscopes, is exemplary and not intended to limit the scope of various embodiments.

When implemented as an accelerometer, the sensor 10 has a normally stable (but movable) mass 24A suspended above the handle wafer 16, and

circuitry 20 for detecting mass movement. The circuitry 20 also may include standard transmit circuitry (not shown in detail) for forwarding information relating to detected mass movement to an external device. Alternatively, the circuitry 20 may be distributed across multiple die/wafers. In some such cases, the sensor 10 may have structure 22 only. Illustrative embodiments, however, integrate the accelerometer functionality (structure 22 and circuitry 20) on a single die/wafer. Exemplary MEMS accelerometer functionality includes those distributed and patented by Analog Devices, Inc. of Norwood, Massachusetts. Among others, see U.S. patent number 5,939,633, the disclosure of which is incorporated herein, in its entirety, by reference.

When implemented as a gyroscope, the sensor 10 has an oscillating mass 24B suspended above the handle wafer 16, and circuitry 20 (shown schematically) for actuating and detecting mass movement. In a manner similar to the above noted accelerometers, the circuitry 20 also may include standard transmit circuitry (also not shown) for forwarding information relating to certain mass movement to an external device. Such circuitry 20 may be on-chip or off-chip. As shown in figure 1, illustrative embodiments integrate the gyroscope functionality (structure 22 and circuitry 20) on a single sensor 10. Exemplary MEMS gyroscope functionality includes those distributed and patented by Analog Devices, Inc. of Norwood, Massachusetts. Among others, see U.S. patent number 6,505,511, the disclosure of which is incorporated herein, in its entirety, by reference.

In accordance with illustrative embodiments of the invention, the sensor 10 has an additional deposited layer (hereinafter, "additional layer 26") formed over the top surface 28 of the device layer 18. At least an air space 30 separates at least a portion of the additional layer 26 from the top surface 28 of the device layer 18. Other components essentially integrated into the device layer 18 thus may be located between that portion of the additional layer 26 and the top

surface 28 (e.g., circuitry 20, such as gate polysilicon and metal leads 21 between circuit elements). To facilitate fabrication, the additional layer 26 illustratively is comprised of a material that conventional micromachining techniques can readily process. For example, the additional layer 26 may be a germanium based material, such as silicon germanium (SiGe).

As noted above and below, the additional layer 26 may be used for a number of different purposes, such as to electrically interconnect parts of the device layer 18, to act as a cap (providing either a hermetic or non-hermetic seal), or to provide electrostatic actuation and detection. In fact, more than one additional layer 26 may be formed for additional functionality. For example, conventional surface micromachining processes may form a second MEMS sensor above the sensor 10 formed on the SOI wafer 12.

Figure 2, which schematically shows a top view of the sensor 10 of figure 1, illustrates exemplary uses of the additional layer 26. Specifically, the additional layer 26 shown includes a first interconnect 32A that couples a first pair of opposed metal contacts 27A, and a second interconnect 32B that couples a second pair of opposed metal contacts 27B. The additional layer 26 also has a grid 34 for electrostatically detecting movement of the mass 24A or 24B. Alternatively, the grid could electrostatically actuate mass 24A or 24B.

Moreover, the additional layer 26 also has a pair of jumpers 36 that electrically connect isolated portions of the device layer 18 across respective air filled trenches 37. This arrangement should minimize parasitic capacitance produced by prior art nitride filled trenches due to the significantly lower dielectric constant of air.

Figure 3 shows an illustrative process of fabricating the sensor 10 shown in figure 1. Figures 4-9 illustrate this process by showing intermediate steps as the sensor 10 is fabricated. This process may be performed on a single SOI wafer 12, or on a bulk wafer that is diced at a later stage. The process begins at step



300, in which conventional processes form structure 22 and circuitry 20 on/into the device layer 18 of the SOI wafer 12. See, for example, figure 4, which shows the SOI wafer 12 with corresponding circuitry 20 and structure 22. More specifically, conventional SOI processes both etch, but do not release, beams on the device layer 18 and form the necessary circuitry 20. For a method of  
5 producing an exemplary SOI device, see commonly owned U.S. patent number 5,569,621, the disclosure of which is incorporated herein, in its entirety, by reference.

The process then continues to step 302, in which a low temperature  
10 sacrificial material 38 is deposited onto the top surface 28 of the device layer 18. As shown in figure 5, this sacrificial material 38 fills beam gaps and other portions etched during previous process steps. Among other things, the sacrificial material 38 may be an oxide, germanium, plated metal, polyimide or other organic material.

15 After it is deposited, the process begins patterning the sacrificial material 38 to act as templates for subsequently formed anchors, contacts, or other structure 22 to be produced by the additional layer 26 (step 304). For example, figure 6 shows holes 39 for contact to metal leads 21 in the circuitry 20 and to the single crystal silicon. Moreover, after patterning the sacrificial material 38, the  
20 process may etch portions of the top surface 28 of the device layer 18, such as a dielectric formed over a metal contact.

The process then continues to step 306, in which conventional processes deposit the additional layer 26 onto the top of the sacrificial material 38 (see figure 7). In illustrative embodiments, the sacrificial material 38 has a deposition  
25 temperature that should not adversely impact the maximum tolerable temperature of components in the device layer 18. For example, the deposition temperature should be low enough to not adversely affect the circuitry 20. In some embodiments, the circuitry 20 is capable of substantially normal operation

even after being subjected to temperatures of up to about 450 degrees C. Accordingly, due to its relatively low deposition temperature, illustrative embodiments use silicon germanium as the additional layer 26. The relative concentrations of polysilicon and germanium are selected to ensure that the  
5 deposition temperature of the additional layer 26 does not exceed about 450 degrees C.

Rather than use a germanium based material, the additional layer 26 could be formed from another material. For example, in embodiments that do not include circuitry 20, the additional layer 26 could be formed from polysilicon,  
10 which has a higher deposition temperature than that of silicon germanium. If used as a particle shield (i.e., without a hermetic seal), a dielectric material can be used, such as silicon dioxide or silicon nitride. Other embodiments may use metal.

The process then continues to step 308, in which conventional surface  
15 micromachining processes pattern the deposited material (i.e., the additional layer 26) to form the desired structure 22. For example, as shown in figures 2 and 8, the deposited material may be patterned to form an anchor, an upper electrode, cap, or particle shield. As shown in figure 8, the anchor 41 may extend and contact the device layer 18 to form an electrical connection.

20 After it patterns the deposited material, the process then removes the sacrificial material 38 in accordance with conventional processes (step 310, figure 9). If the sacrificial material 38 is germanium, then a number of etchants typically used for germanium etching may be used. For example, hydrogen peroxide may be used. Alternatively, the process may use oxygen plasma if the sacrificial  
25 material 38 is an organic. Removal of the sacrificial material 38 forms an air space 30 between the deposited material and the top surface 28 of the device layer 18. In other words, the air space 30 effectively spaces the additional layer

components (formed by first etching the deposited material and then removing the sacrificial material 38) from the top surface 28 of the device layer 18.

Finally, the process ends after step 312 by releasing the MEMS structures in the device layer 18. If the deposited material merely forms simple  
5 interconnects and anchors, existing resist pedestal release processes may be used. If it forms a cap, however, a vapor hydrofluoric acid or other technique may be used. Those in the art should be capable of selecting the appropriate release process. Those discussed above are merely exemplary of various embodiments.

Those in the art understand that other steps can be performed in addition  
10 to those discussed above. For example, various preprocessing (e.g., preparing the SOI-wafer 12) and post-processing steps (e.g., testing, packaging, etc...) can be performed.

As noted above, rather than have a single additional layer 26, some embodiments have multiple additional layers. Aspects of this process thus can  
15 be used to fabricate such a multi-layer device. Accordingly, additional deposited and sacrificial layers can be added and still be consistent with the goals of various aspects of the invention.

Illustrative embodiments of the invention thus enable single crystal based sensors to perform out of plane actuation and sensing (i.e., perpendicular to the  
20 plane of the mass 24A or 24B). In addition, illustrative embodiments also enable such sensors to more easily interconnect various portions of the device layer 18. Due to their fabrication methods (discussed above), some of those interconnects enable use of an air filled trench (e.g., see figure 2) between isolated portions of the device layer 18 rather than a material filled trench (e.g., nitride filled).  
25 Moreover, as also noted above, some embodiments form robust in-situ caps.

Although the above discussion discloses various exemplary embodiments of the invention, it should be apparent that those skilled in the art can make various modifications that will achieve some of the advantages of the invention  
5 without departing from the true scope of the invention.